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Physical and geometrical non-linear behavior of precast beams on elastomeric supports

Comportamento não linear físico e geométrico de vigas pré-moldadas sobre apoios elastoméricos



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Abstract

The stability of long and slender precast beams has been associated with structural collapse during the transitory phase of construction. The inevitable deviations regarding the execution between the support cross-section and midspan aggravate the instability problem, thus causing the beams to become even more susceptible to its effects. The focal point of this study is the numerical and behavioral evaluation of concrete beams that present geometric imperfections on elastomeric supports and analyze the influence exerted by the variables of: strength characteristics of concrete, physical non-linearity of the concrete and the compression stiffness of the bearing pad. The numerical analyses were developed on a computer program based on the finite element method (FEM). Among the principle conclusions drawn from the study, one finds that the increase in the characteristic strength of the concrete provides the beam with a higher degree of stability, and the consideration of the physical non-linear behavior of the material did not allow the equilibrium point on the numerical model to be found in some of the cases that were evaluated. The rotational stiffness of the pad decreases as the skew angle increases. Therefore, one needs to remember that in very critical situations, it may not be possible to find the point of equilibrium, thus leading to collapse.

Keywords: stability, bearing pad, stiffness, equilibrium, toppling.

Resumo

A estabilidade lateral de vigas pré-moldadas longas e esbeltas tem sido associada a colapsos durante as fases transitórias de montagem. Os inevitáveis desvios de execução entre a seção transversal do apoio e a do meio do vão agravam e tornam mais suscetíveis os problemas de instabilidade. O objetivo deste trabalho é avaliar numericamente o comportamento de vigas de concreto que apresentam imperfeições geométricas sobre almofadas de apoio de elastômero e analisar a influência de variáveis, como: resistência característica do concreto, não linearidade física do concreto e rigidez à compressão da almofada. As análises numéricas foram desenvolvidas em um programa computacional baseado no Método dos Elementos Finitos. Dentre as principais conclusões, percebeu-se que o aumento da resistência característica do concreto confere à viga maior estabilidade e que a consideração do comportamento não linear físico do material não permite encontrar uma posição de equilíbrio no modelo numérico em alguns casos avaliados. A rigidez ao giro da almofada diminui na medida em que o ângulo de esconsidade aumenta. Deve-se ter em mente que, em situações muito críticas, pode não ser possível encontrar equilíbrio para a viga, levando ao seu colapso.

Palavras-chave: estabilidade, almofada, rigidez, equilíbrio, tombamento.

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1. Introduction

Precast concrete beams, in light of the suspension equipment as well as the limitations of the transport vehicles, have presented cross-sections with better mechanical efficiency. Furthermore, these elements are demanded by the very forces of the transitory phase, such as handling, along with lifting and transport. Even the characteristics of public roads (superelevation and curves) and the damping system of the transport vehicle can affect the stability and the security of these beams.

When the beam is seated in its resting position on the structure over deformable supports, although without any real connection or lateral bracing, there can still occur problems related to lateral instability. In a majority of cases, the beams are supported on elastomeric supports, flexible and deformable, which may not be able to resist rigid body rotation of the beam, and in more critical situations not resist toppling.

The presence of geometric imperfections on the beam, due to the inevitable errors during concreting, prestressing or from different heat sources during thermal curing aggravate and heighten the probability of instability problems. The beam presents, from its initial conception, a curved form that is not foreseen in the project, as for example that which occurs due to the deviation of the support cross-section in relation to the midspan, and through such is more susceptible to toppling and rigid body rotation.

In the Literature, it is possible to find authors that report the occur-



Skew

angle

t

Support centerline

rence of accidents with precast beams during the handling transitory phase, which are related to the lateral instability of these elements. The studies by Tremblay & Mitchell [1], Oesterle et al. [2] and Bairán & Cladera [3] analyze the collapse of beams on deformable supports and reported that the cause was due to insufficient lateral bracing for withstanding the rigid body rotation of the beam or to the incorrect sizing and positioning of the bearing pad support on the structure. A recent case occurred in Brazil in 2014, with the collapse of a beam on the monorail in São Paulo, which had already been positioned onto the structure.

The authors Burgoyne & Stratford [4] and Plaut & Moen [5] deal with lateral instability of precast concrete beams on deformable supports and show that the deformability of the support influences the equilibrium and stability of the beam. When one analyses the problem of lateral instability of concrete beams, it is necessary to take into consideration conditions that are as close as possible to real conditions. Hence, there are those geometric variables that are of extreme importance in the analyses.

According to Consolazio & Hamilton [6], the lateral eccentricity or geometric imperfection presented in

Figure 1, is the lateral displacement between the straight beam and the real configuration in curved form. This lateral displacement can arise from deviations during prestressing and on the prestressed cables, deviations in the positioning of the molds and during concreting as well as in heat sources, as in the different sources of heat during thermal curing. In Figure 2, the skewness of the support is the angle formed between the longitudinal axis of the route taken (roadway) and the central line of the support. Mainly in prestressed beams, it is common to see a vertical curvature between the longitudinal axis of the beam on the support and the surface of the bearing pad support (Figure 3).

In this sense, the objective behind this study is to evaluate the lateral stability of the AASHTO Type IV beam on FDOT Type A and FDOT Type B bearing pads, through considerations made with different initial geometric imperfections during handling. Furthermore, an evaluation will be made concerning the influence of the strength characteristic of the concrete and its physical non-linearity and stiffness to compression of the elastomeric bearing pad, keeping in mind the partial contact loss between the beam and the support device. Finally, the stiffness of the bearing pad to rotation is estimated for the different skewness angles.





Figure 2

Skewness of the support Source: Adapted from Consolazio & Hamilton (2007)

2. The AASHTO Type IV beam on laminated bearing pads

This work conducted a numerical analysis on the ANSYS computer program [7], which is based on the Finite Elements Method. The beam section was defined as a standard AASHTO Type IV, as presented in Figure 4, at 32 m in length, supported on FDOT Type A and FDOT Type B standard bearing pads, for which the dimensions are presented on Table 1.

The AASHTO Type IV beam was analyzed with different initial geometric imperfections. The centroid position deviations of the crosssection at midspan relative to its intended position on the supports are presented on Table 2 and in

Figure 1. It started out by adopting a maximum eccentricity at the midsection of the beam in relation to the supports permitted by the PCI [8]: 1 cm for every 10 m of beam length. Analyses were also made of the eccentricities close to field measurements as in Cojocaru [9], and in a complementary manner, analysis was made of a very critical and unfavorable situation, where the values of 13.5 cm and 18 cm were adopted. The authors Burgoyne & Stratford [4] recommend working with values for initial geometric imperfections in the order of L/1000, where L is the total length of the beam. In the Eurocode [10], it is suggested that for braced beams in the transport and handling phase, a geometric imperfection in the order of L/300 is adopted.

In order to numerically represent the elastomeric bearing pads, the decision was made to adopt the simplified model proposed and experimentally evaluated by Harper & Consolazio [11], and discussed and calibrated in Cardoso [12]. In this model, the bearing pad is considered as a rigid grill responsible for joining springs of different stiffness when subjected to axial compression. This model of grill divides the bearing pad into small rectangular regions and for each there is associated a compression spring that is of a different stiffness from the others. Springs were employed that worked entirely compressed, in a way that traction requests result in no support reaction on the spring. Thus, it is possible to contemplate the partial loss of contact between the beam and bearing pad.

In the present study, the FDOT Type A and FDOT Type B bearing pads are considered with standardized size and characteristics, for which the stiffness when subjected to axial compression are respectively 10991 kN/cm and 12512 kN/cm. Bearing pad A is designed as a grill with 105 compression springs (7×15), and an area region

Table 1

Dimensions and characteristics of the analyzed bearing pads

Dimonsion (obaractoristic	Bearing pad				
Dimension/characteristic	Α	В			
Length, L (cm)	60	60			
Width, W (cm)	28	36			
Height, H (cm)	4.8	6.5			
Quantity of steel plates	3	4			
Source: Authors (2017)					



Figure 4

Modified cross-section of the AASHTO Type IV beam **Source:** Authors (2017)

equal to 16 cm². Bearing pad B is designed with a grill containing 135 compression springs (9×15), with an area equal to 16 cm². Figure 5 presents the rigid grills for bearing pads A and B, and Figure 6, the distribution of the stiffness on the bearing pads A and B. The values for stiffness to compression and the final considerations prepared in the numeric models are the same as those presented in Cardoso [12].

Guarantees were made to see that the nodes from the lower table of the beam coincided exactly with the nodes on the bearing pad in accordance with the simplified model. For the beam, the threedimensional element SOLID65 was employed and for the bearing pad springs, the LINK180 was employed.

Under the beam on supports setup, the only loading that acts on the structure is its own weight, which was applied by the inertia command from ANSYS [7]. In all of the analyses performed, the geometric non-linearity was considered as being very important in lateral instability problems.

Three strength values characteristic of concrete were adopted (f_{ck}) , namely: 27.5, 45 and 90 MPa. The initial concrete elasticity

Table 2

Initial lateral eccentricities adopted

Beam	Initial eccentricity (e _i)				
	Absolute (e _i) (cm)	Relative (e _i /L)			
B1	1.0 (L/3200)	0.0003			
B2	3.0 (L/1067)	0.0009			
B3	3.2 (L/970)	0.0010			
B4	5.0 (L/640)	0.0016			
B5	6.6 (L/485)	0.0021			
B6	9.0 (L/356)	0.0028			
B7	13.5 (L/237)	0.0042			
B8	18.0 (L/178)	0.0056			
Source: Authors (2017)					



Rigid grills for bearing pads A and B source: Authors (2017)

models adopted for the beam were respectively, 2936.67, 3756.59 and 5312.63 kN/cm², with a Poisson coefficient equal to 0.2 and a specific weight of 25 kN/m³. The behavior of the concrete to compression was considered through the parabola-rectangle diagrams, without softening.

It is of importance to emphasis here that in the pre-service situation, it is expected that the beam is not cracked. However, in practice one knows that it is possible that the beam cracks due to forces arising from handling and transport until its final resting position. Furthermore, even when the beam is on support bearing pads, the forces generated in the concrete due to rigid body rotation and the toppling of the beam lead to cracking and loss in strength capacity. Therefore, aimed at representing the strength capacity loss of the beam and the non-linear behavior of the concrete, a physical non-linear analysis was performed on ANSYS [7]. The model *concrete* from the very SOL-ID65 element was used. The force-deformation curve was obtained by the definition of the six points, for which the coordinates were calculated through parametric equations that relate to the characteristic strength of the concrete and its initial or tangent elasticity module. In order to use the model *concrete* on ANSYS [7], it was necessary to define four parameters relevant to the behavior of drawn and compressed concrete. The first two refer to the shear stress transferred to the open and closed crack. For these variables, the values of 0.2 and 1.0 were adopted, respectively. The two remaining parameters are related to the cracking and crushing stress of the concrete, for which the values were defined as one tenth of the concrete strength and (-1.0), respectively.

3. Results and discussions

3.1 Non-linear geometric analysis

Initially, a static analysis was performed that considered the geometric non-linearity, which is necessary to simulate the exclusive effect of compression on the springs of the simplified model of the bearing pads. In this analysis, the support reactions on the springs were obtained for each of the eight beams analyzed, for each of the three evaluated f_{ck} and for each of the bearing pads under



Stiffness distribution Source: Authors (2017) consideration. In Figures 7 and 8, the hatched area represents the region of the bearing pad on the left-hand side of the beam (

Figure 1), where there is no support reaction, or be it, the loss of contact between the beam and the bearing pad. Note also the offset of the result for the vertical support reaction on the elastomeric support, which deviates from the central region.

The characteristic strength of the concrete confers contact loss protection between the beam and bearing pad. The degree at which f_{ck} increased toward 90 MPa, it was noted that there was no contact loss between the beams B1, B2 and B3 and bearing pad A, which was not verified for lower values of f_{ck} . Furthermore, for the most critical case represented by beam B8, there is a gain of 6% in

bearing pad area, which effectively resists the rigid body rotation of the beam when compared to the hatched region in

Figure 7 for the beam with f_{ck} = 27.5 MPa and f_{ck} = 90 MPa. As seen on bearing pad A, one also notes that for bearing pad B, the characteristic concrete strength of the beam plays an important role in the stability of the element in terms of toppling. Higher values of f_{ck} reduce the contact loss between the beam and the bearing pad, thus a greater area of the bearing pad effectively works in balancing the rigid body. Taking as a reference beam B3, for which the initial eccentricity was considered as the limit established by the PCI [8], for f_{ck} = 27.5 MPa, one has a contact loss of 23% of the bearing pad area. Next, for f_{ck} = 45 MPa, this value is reduced



to 13%, and for f_{ck} = 90 MPa, one has a bearing pad area of 3.7%, where there is no contact with the beam.

The maximum vertical and horizontal displacements obtained at the beam midspan are presented in Figures 9 and 10, respectively. In a general sense, one notes that the increase in compression stiffness of the bearing pad, provided when using bearing pad B, led to slightly lower vertical displacements in all cases. In addition, one notes here that the influence of concrete strength is also beneficial, since it reduces in almost twice the value the maximum vertical displacements measured on the cross-section of the beam midspan.

The increase in the concrete strength and the use of a bearing N pad of higher compression stiffness (bearing pad B) confer less f_{d}

horizontal displacements to the beam in the middle of its span. The effect of the initial imperfections was felt most strongly on the horizontal displacements than on the vertical displacements. One notes from

Figure 10, that the variation of the horizontal displacement in regards to the variation of the initial imperfection was greater for the beams that presented higher initial lateral displacements.

3.2 Geometric and physical non-linear analysis

Numerically, in the non-linear analyses with the eight beams with f_{ck} = 27.5 MPa and with the beams B7 and B8 with f_{ck} = 45 MPa, no



position of equilibrium was encountered. For $f_{ck} = 90$ MPa, results were obtained for the eight eccentricities evaluated. Once more, the strength and stiffness of the concrete provide the structure protection and leads to the equilibrium of the beam face through lateral stability.

The value of the support reaction with the inclusion of the physical non-linearity of the concrete was maintained equal to that verified by the geometric non-linear analysis, which respected the static balance condition.

Figures 11 and 12 present the maximum vertical and horizontal displacements obtained at the midspan for geometric non-linear analysis, as well as those already presented for geometric non-linear analysis.

Noted here is that the geometric and physical non-linear analysis presented displacement values close to those obtained in the geometric non-linear analysis. The contribution of increasing the characteristic strength of the concrete is also observed here, except in those cases that did not converge.



Of ck = 27.5 MPa (B)
$$\Box$$
 fck = 45 MPa (B) \land fck = 90 MPa (B)

Figure 9

Maximum vertical displacements Source: Authors (2017)





Figure 10

Maximum horizontal displacements Source: Authors (2017)



Figure 11

Maximum vertical displacements with physical non-linear analysis Source: Authors (2017)

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Figure 12

Maximum horizontal displacement with physical non-linear analysis Source: Authors (2017)

The maximum horizontal displacements measured in the non-linear geometric and physical analysis were higher than those obtained only in the geometric non-linear analysis. This difference was small, but sharper when compared with the vertical displacements. In the same manner, the contribution of the highest characteristic strength of the concrete is maintained along with the most important effect of the increase in initial geometric imperfections on horizontal displacements than on vertical displacements.

3.3 Determining rigid body rotation for different angles of bearing pad skewness

The AASHTO Type IV beam was analyzed with eight different initial eccentricity values as presented on Table 2. Each beam was modelled with an arc, and each arc had associated to it an initial angle (a_1), as presented in Figure 13.

Therefore, in regards to the global coordinate system (x and z), there arise two new axes obtained (x' and z') rotating the previous from a_1 . As a result of the support reaction on the bearing pad, this becomes displaced in respect to the axes x' and z', hence two bending moments are generated around these axes (M_x and M_z), as presented in Figure 14.





In order to determine the rigid body rotation in the skewed condition, the first step consists of obtaining the values of the bending moments. Through knowledge of the reactions on each spring of the simplified model, it was possible to determine the result of the support reaction and its position on the bearing pad, and thus obtain the values of the bracing moments (a and b) presented in Figure 14, along with the value of the bending moments.

Following this, the rotations were determined for the axes directions x' and z'. As a result of the numerical model, the rotations in x (ROTX) and in z (ROTZ) were obtained from ANSYS. Through these rotations, its components on the axes x' and z' were calcu-



Figure 14

Bending moments generated by the reaction of the support on the bearing pad Source: Authors (2017)

lated, in order to obtain the rotation ψ on the z'-axis and rotation ϕ on the x'-axis, as presented in Figure 15.

Through the values for moment and rotation on the axes x' and z', the resulting moment and rotation for each one of the eight beams analysed were obtained. The stiffness to rotation under the occult bearing pad condition was determined by producing the quotient between the resulting moment to the resulting rotation.



Rotations on axes x' and z' Source: Authors (2017)

Beam	Angle (a1) (degree)	Rotational stiffness (kN·cm/rad)				
		Bearing pad A	Bearing pad B	Bearing pad A with NLF	Bearing pad B with NLF	
B1	0.071	3.78E+06	3.95E+06	3.79E+06	3.91E+06	
B2	0.212	3.72E+06	3.91E+06	3.71E+06	3.86E+06	
В3	0.233	3.70E+06	3.89E+06	3.70E+06	3.85E+06	
B4	0.354	3.61E+06	3.81E+06	3.59E+06	3.76E+06	
B5	0.467	3.49E+06	3.72E+06	3.47E+06	3.67E+06	
B6	0.637	3.29E+06	3.55E+06	3.26E+06	3.49E+06	
В7	0.955	2.87E+06	3.13E+06	-	-	
B8	1.273	2.43E+06	2.68E+06	-	_	
jource: Authors (2017)						

Table 3 Rotational stiffness obtained for beams with $f_{ck} = 45$ MPa

The stiffness to rotation coefficients were calculated for the eight beams with $f_{ck} = 45$ MPa, through a consideration of the results obtained only with the geometric non-linear analysis as well as those obtained through the geometric and physical non-linear analysis. Table 3 and Figure 16 present the stiffness to rotation obtained for each beam, through the consideration or not of the physical non-linearity of the concrete. There are no results presented for beams B7 and B8, as the solution does not converge on the numerical model of these beams when the characteristic strength value of the concrete was equal to 45 MPa.

As expected, greater skewness angles lead to lower coefficient values of stiffness to bearing pad rotation. The action of the bending moments in both directions of the bearing pad reduce the capacity of the bearing pad to resist rigid body rotation of the beam and impairs lateral stability in view of the toppling of the beam. The skewness angles considered in this work are small, since these are due to the geometric imperfections, but in the case of curved beams, the influence of this parameter makes this fact significant. Noteworthy still is that Burgoyne & Stratford [5] stated in their work that the stiffness necessary for the bearing pad can be eas-



Figure 16 Rotational stiffness × skewness angle of the bearing pad Source: Authors (2017)

ily calculated and should be adequately specified in the project. However, due to the high and complex interaction of the geometric imperfections of the beam, misalignment of supports and buckling modes, it is desirable that one has a high safety margin (it is for this reason, the authors recommend a high safety factor) from the stiffness to rotation given by the bearing supports. Furthermore, it is necessary to take care and stick to the centralized positioning of the beam on the support device.

4. Conclusions

The reports of accidents and beam collapses in the Literature associate these problems to the lateral instability of precast beams during the transport phase. In this manner, the study of the subject and reaching an understanding as to the different variables that influence the behavior of the beams is of the upmost importance. The simplified model adopted in this work presented a satisfactory response to the main considerations that should be taken into account when working with beams on deformable supports. The use of compression springs allowed for the simulation of contact loss between the beam and the elastomer, which generated a position

change in the reaction of the support on the bearing pad. The developed analyses allowed for the quantification of the combined effect of the parameters, such as initial geometric imperfection, stiffness of the beam and physical non-linear effects of the concrete. The main conclusions of this study were:

- a) In the geometric non-linear analysis, the increase in the characteristic strength of the concrete, and consequently the stiffness of the beam, led to less displacements and less areas with contact loss between the beam and the bearing pad.
- b) The consideration of the physical non-linear behavior of the material (to the cracking of the concrete) showed that for the lowest concrete strength value, the numerical model did not find equilibrium. In terms of the intermediary concrete strength, this also occurred to the two highest values of initial imperfections, and for the highest concrete strength, it was possible to arrive at equilibrium over all values of initial imperfection.

- c) The rotational stiffness of the bearing pad decreased at the rate that the eccentricity of the beam increased, or be it, the rate at which higher bending moments began to act on both directions of the support device.
- d) The presence of initial geometric imperfections generate a skewness angle that interferes with the rotational stiffness of the bearing pad, when considering as a reference the beam with the initial imperfection limit as established by the PCI [8]. Initial imperfection limits that exceed this limit by five times can bring about a reduction by around 22% in the stiffness to rotation.

Future analyses that take into consideration distortions on the bearing pad, the vertical curving of the beam and the effect of possible forces due to wind can lead to a more profound evaluation of the problem.

This work shows the importance that should be given to geometric imperfections of long and slender precast beams in the analyses of instability during the handling phase. It is necessary to be aware of the fact that the increase in the midspan curve, caused by the presence of initial imperfections, generates an increase in stresses on the beam that normally are not considered during the project. These stresses can become significant when the stiffness of the support is reduced, thus suggesting that a higher safety factor be employed by means of choosing the most adequate support bearing pad. In those more severe cases, the higher stresses can create cracking in the concrete, thus reducing the stiffness of the beam and causing sudden collapse.

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